THE UZAWA LUCAS MODEL

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SOCIAL PLANNER PROBLEM

In this version of the model (Cf B&S 5.2.2) there are no externalities. Hence, we go straight at the Social planner problem

$$\max \int_{0}^{\infty} \ln c_{t} e^{-\rho t} dt$$
$$c_{t} \ge 0, u_{t} \ge 0$$
$$\dot{K} = Y - C - \delta K$$
$$Y = K^{\alpha} (uH)^{1-\alpha}$$
$$\dot{H} = B (1-u) H - \delta H$$
$$K_{t} \ge 0, H_{t} \ge 0 \text{ for all } t$$

Control v.: State v.:

The Hamiltonian

$$H(c, u, H, K, \lambda_K, \lambda_H, t)$$

= $\ln c_t e^{-\rho t} + \lambda_K \left[K^{\alpha} (uH)^{1-\alpha} - C - \delta K \right] + \lambda_H \left[B (1-u) H - \delta H \right]$
FOC

$$c:\frac{1}{c}e^{-\rho t} = \lambda_k$$
$$u:\lambda_k (1-\alpha)\frac{Y}{u} = \lambda_H BH$$
$$H:\lambda_K (1-\alpha)\frac{Y}{H} + \lambda_H [B(1-u) - \delta] = -\dot{\lambda}_H$$
$$K:\lambda_K \left[\alpha\frac{Y}{K} - \delta\right] = -\dot{\lambda}_K$$

Usual manipulations lead to the K-R rule

$$\frac{\dot{C}}{C} = \gamma_C = \alpha \frac{Y}{K} - \delta - \rho$$

in addition we have

$$\gamma_H = B\left(1-u\right) - \delta$$

and

$$\gamma_K = \frac{Y}{K} - \frac{C}{K} - \delta$$

A Balanced growth path is quantities $\{Y, C, H, K, u\}_0^\infty$ and prices $\{\lambda_K, \lambda_H\}_0^\infty$ such that $\gamma_j = \gamma_i$ for all $i \neq j$ where i, j = Y, C, H, K; λ_K/λ_H is constant and u = constant.

Our strategy is simply to impose this requirement, and derive the growth rate of the economy as well as $u = u^*$.

Step 1: Find $\alpha (Y/K)^*$ Use H'_u : $\frac{\lambda_k}{\lambda_H} = \frac{BuH}{(1-\alpha)Y}$

and H'_H

$$\begin{split} -\gamma_{\lambda_{H}} &= \frac{\lambda_{K}}{\lambda_{H}}(1-\alpha)\frac{Y}{H} + B\left(1-u\right) - \delta \\ &= \frac{BuH}{\left(1-\alpha\right)Y}\left(1-\alpha\right)\frac{Y}{H} + B\left(1-u\right) - \delta = B - \delta \end{split}$$

Finally, imposed balanced growth: $\gamma_{\lambda_H} = \gamma_{\lambda_K}$ and use H'_K

$$-\gamma_{\lambda_K} = \alpha \left(\frac{Y}{K}\right)^* - \delta = -\gamma_{\lambda_H} = B - \delta$$

Hence

$$\alpha \left(\frac{Y}{K}\right)^* = B$$

Observe that this implies $\gamma_K^* = \gamma_Y^*$, and that the growth rate of C

$$\gamma_C^* = B - \delta - \rho.$$

Step 2: Show $\gamma_K^* = \gamma_C^* = \gamma_Y^*$. This follows since:

$$\gamma_K^* = \left(\frac{Y}{K}\right)^* - \left(\frac{C}{K}\right)^* - \delta$$

so $\gamma_K^* = \gamma_C^* = \gamma_Y^*$.

Step 3: get u^* Begin by noting that (from H'_c)

$$\frac{\lambda_k}{\lambda_H} = B \frac{uH}{(1-\alpha) Y}$$

So $\frac{\lambda_k}{\lambda_H}$ = constant requires H/Y to be constant, for u constant. Hence $\gamma_H^* = \gamma_Y^* = \ldots = \gamma_c^*$. Next, use \dot{H} equation

$$\gamma_H^* = B\left(1 - u^*\right) - \delta = \gamma_Y^* = B - \delta - \rho$$

Which leads to

$$u^* = \rho/B.$$

which completes the solution for the balanced growth path

Some remarks on transitional dynamics

Consider the imbalance effect noted in the "simple" Uzawa-Lucas model. We need to figure out the transitional dynamics of Y/K; then we will know how C behaves, and as it turns out, $Q \equiv Y + \lambda_H \dot{H}$ From the production function we find that

$$\frac{Y}{K} = \left(\frac{uH}{K}\right)^{1-\alpha}$$

in addition H_u gives us

$$\begin{aligned} \frac{\lambda_k}{\lambda_H} &= B \frac{uH}{(1-\alpha)Y} = B \frac{uH/K}{(1-\alpha)Y/K} = B \frac{(Y/K)^{1/(1-\alpha)}}{(1-\alpha)Y/K} \\ &= \frac{B}{1-\alpha} (Y/K)^{\frac{\alpha}{1-\alpha}}. \end{aligned}$$

e, $\gamma_{\lambda_k} = \frac{\alpha}{1-\alpha} \gamma_{Y/K}. \end{aligned}$

Hence, $\gamma_{\frac{\lambda_k}{\lambda_H}} = \frac{\alpha}{1-\alpha} \gamma_{Y/K}$.

Now $-\gamma_{\lambda_H} = B - \delta$ and $-\gamma_{\lambda_K} = \alpha \frac{Y}{K} - \delta$. Hence, using this and the fact that $\gamma_{\frac{\lambda_k}{\lambda_H}} = \frac{\alpha}{1-\alpha} \gamma_{Y/K}$:

$$\gamma_{\lambda_K} - \gamma_{\lambda_H} = \frac{\alpha}{1 - \alpha} \gamma_{Y/K} = -\alpha \frac{Y}{K} + \delta + B - \delta$$

SO

$$\gamma_{Y/K} = \frac{1-\alpha}{\alpha} \left[B - \alpha \frac{Y}{K} \right] = (1-\alpha) \left[\frac{B}{\alpha} - \frac{Y}{K} \right]$$