Does Tax Competition Really Promote Growth?

Marko Koethenbuerger and Ben Lockwood

Abstract

This paper considers the relationship between tax competition and growth in an endogenous growth model where there are stochastic shocks to productivity, and capital taxes fund a public good which may be for final consumption or an infrastructure input. Absent stochastic shocks, decentralized tax setting (two or more jurisdictions) maximizes the rate of growth, as the constant returns to scale present with endogenous growth implies “extreme” tax competition. Stochastic shocks imply that households face a portfolio choice problem, which dampens down tax competition and may raise taxes above the centralized level. Growth can be lower with decentralization. Our results also predict a negative relationship between output volatility and growth with decentralization.

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Mailing Address: Department of Economics, University of Copenhagen, Studiestraede 6, DK 1455 Copenhagen, Email: marko.koethenbuerger@econ.ku.dk.

Mailing address: Department of Economics, University of Warwick, Coventry CV4 7AL, England. Email: B.Lockwood@warwick.ac.uk
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1. Introduction

The link between fiscal decentralization and economic growth is increasingly attracting the attention of economists. In particular, a growing body of empirical research is investigating the links between measures of fiscal decentralization and growth, both at the country and sub-national level. Overall, the evidence is mixed. In particular, cross-country studies, which generally use similar measures of fiscal decentralization, can find positive or negative effects, depending on precise measure of decentralization, sample, estimation method, etc. (Davoodi and Zhu, 1998, Woller and Phillips, 1998, Zhang and Zou, 1998, Iimi, 2005, Thornton, 2007). More recently, two studies on US data have found more robust evidence that fiscal decentralization increases growth (Akai and Sakata, 2002, Stansel, 2005). For example, Stansel (2005), in a study of growth over 30 years in 314 US metropolitan areas, has found that the degree of fractionalization (the number of county governments per million population in a metropolitan area) significantly increases growth.

On the theoretical side, explanation of the mechanisms linking fiscal decentralization and growth are thin on the ground. Two mechanisms have been studied. First, as shown by Hatfield (2006), tax competition can raise the post-tax return on capital, thus increasing the return to savings, and thus growth, in an endogenous growth model. Second, Brueckner (2006) shows that centralization, if it imposes uniform public good provision across regions, can lower the rate of savings and thus growth, although this mechanism appears to require difference in the mix of young and old across fiscal jurisdictions.

This paper makes a contribution to understanding of the tax competition mechanism.
We set up a multi-jurisdiction endogenous growth model which combines two empirically relevant motives for investing outside the jurisdiction, namely rate-of-return arbitrage and portfolio diversification. The latter motive is absent in standard tax competition models which only take rate-of-return differentials as the driving force for investing abroad. The former motive accounts for the well-known positive fiscal externality in tax competition: a higher capital tax rate causes capital to flow to other jurisdiction and expands the tax base therein. The consequence is that taxes will be set at an inefficiently low level. To create demand for portfolio diversification we assume that there are independent stochastic shocks to production in each of $n$ regions. This generates stochastic returns to capital invested by a household in each region.

So, if taxes are not too different, the household located in one region will want to invest some of its accumulated capital in all regions. This in turn generates a negative fiscal externality: an increase in the capital tax in any “foreign” region reduces the return on capital invested in that region. Specifically, because the “home” household will not wish to withdraw all of its savings from the foreign region in response to higher taxes, in order to maintain a diversified portfolio, its interest income will go down. The key point is that this negative “rate-of-return” externality offsets the usual positive fiscal externality arising from mobile capital (i.e. that an increase in the foreign region’s tax leads to a capital outflow from the foreign region to the home region). This implies that when the second externality dominates, taxation under decentralization will be higher, and growth lower, than with centralization. In the simple AK version of our growth model, in which a consumption public good is financed out of a tax on capital, analytical results show that
this occurs when (i) the number of regions is small; (ii) when the variance of the shock is sufficiently high.

We then modify the AK model to the Barro (1990) model of infrastructure growth in which we allow the production technology to be stochastic. This has the consequence that the pre-tax rate of return to capital in a region becomes more variable as the tax and thus the amount of infrastructure good in that region increases. This specification introduces a third type of externality of decentralized government policy, not seen in the literature on fiscal competition so far, which we call the risk-exposure externality. Specifically, a higher tax increases the riskiness of investment and thus the risk-bearing of non-residents. The risk-exposure externality is negative and, thus, counteracts the tendency of taxes to race to the bottom in fiscal competition. As to growth, we find, consistently with Alesina and Rodrik (1994), that absent stochastic shocks, centralization yields a tax rate which is too high to be growth maximizing, while decentralization yields a tax rate which is growth maximizing. By a continuity argument, growth is higher under decentralized government when the variance of the shock is small. But, as the variance of the shock increases, centralization may generate higher growth than decentralization, as in the consumption public good case.

One of the interesting predictions of our model concerns the relationship between the variance of stochastic shocks and growth. With a public consumption good, we show analytically that growth is (at least weakly) decreasing in the variance of the output shock. With a public infrastructure good, and fiscal decentralization, simulation results indicate a negative relationship between growth and the variance of output shock. This is
consistent with the macroeconomic evidence (see Ramey and Ramey, 1995), although of
course there are other mechanisms linking output shocks and growth (Jones and Manuelli,
2005).

Finally, the question arises as to why we need stochastic shocks and portfolio diver-
sification as the mechanism for generating a countervailing negative externality in our
endogenous growth model. After all, there are various other mechanisms (see Section 2)
that tend to raise taxes above the socially optimal level in static tax competition models.
The answer is the following. In the AK-type growth model without stochastic shocks,
the firm’s demand for capital is perfectly elastic at the tax-inclusive price of capital. This
in turn, under the standard assumption of perfect mobility of capital across regions (also
made in this paper) implies “extreme” or Bertrand tax competition: each jurisdiction can
undercut the others by a fraction and capture all the capital in the economy (Hatfield,
2006). This extreme competition dominates other mechanisms (such as tax exporting)
which tend to raise taxes. Stochastic shocks, by contrast, have two effects. As already
pointed out, they generate the countervailing rate of return externality. But also, they
weaken the tax undercutting incentive; a small cut in tax will now only lead to a small
capital inflow. So, we would say that stochastic shocks are the only means by which a
micro-founded model can generate higher taxes and lower growth under decentralization.

The rest of the paper is organized as follows. Section 2 discusses the related literature.
Section 3 introduces the model, solves for equilibrium conditional on fixed government
policy, and identifies the fiscal externalities at work in the model. Section 4 contains the
main results. Section 5 modifies the model to include infrastructure public goods. Section
2. Related Literature

The static tax competition literature emphasizes several mechanisms which can offset, or even dominate, the basic positive mobile tax base externality. For example, foreign ownership of fixed factors can lead to a tax exporting incentive to raise taxes (Huiizenga and Nielsen, 1997). Or, if countries are asymmetric, capital importers wish to set higher taxes in order to lower the cost of capital (Bucovetsky, 1991, and Wilson, 1991). Neither of these mechanisms apply here. Fixed factors (if present) are owned by domestic residents, and since the model is symmetric and we confine attention to symmetric equilibria, net trade in capital is zero in equilibrium.

In a more closely related contribution, Lee (2004) studies the impact of stochastic output shocks on tax competition in the usual static model of mobile capital. However, in his model, as the number of regions is assumed large, investors can be sure of a certain return on capital, and only face uncertain wage income. Thus, the negative externality arising though portfolio choice which is studied here does not arise in his model; his focus is on the fact that capital taxes can provide insurance against random fluctuations in wages, and thus will be used even a fixed factor can be taxed directly.¹

Related literature on economic growth and public finance is as follows. We have already noted that in the AK model, absent uncertainty, with decentralization, Bertrand

¹See also Wrede (1999) for an analysis of fiscal externalities in dynamic economies. But, his paper abstracts from portfolio diversification and endogenous growth.
tax competition will drive taxes down to zero and maximize growth. Hatfield (2006) has shown that a similar conclusion holds very generally in Barro’s (1990) model of infrastructure growth: that is, there is a tax-inclusive price of capital at which firms are willing to employ any level of the capital input. So, the allocation of capital is determined by households, who move capital to the region with the highest price. Thus, again there is extreme or Bertrand tax competition: jurisdictions compete to set taxes to achieve the highest pre-tax price of capital. As there is an infrastructure public good funded by the capital tax, this price-maximising tax is not zero, but strictly positive. Nevertheless, the conclusion is the same as in the AK model: under decentralization, the rate of return on savings, and thus the growth rate is maximised.

Second, Lejour and Verbon (1997) address the issue of (de)centralization and growth in a deterministic AK growth model. Capital is made imperfectly mobile between regions by the assumption of an ad hoc convex mobility cost of moving capital between regions. Moreover, built into the cost function is an ad hoc “preference for diversification”. But, an explicit analysis of portfolio diversification is lacking in their analysis.

Third, Wildasin (2003) and Becker and Rauscher (2007) study dynamic tax competition models in a deterministic environment where there is a convex cost of adjusting the physical capital stock over time, but where the household’s financial capital is per-

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2 This holds even when labour supply is endogenous and is taxable, when there are consumption and infrastructure goods, and where agents are different within regions (with respect to their endowments of capital) and decisions are made by majority voting.

3 Formally, if $s$ is the share of capital invested outside the home region, the mobility cost is $c(s) = -vs + \mu s^2/2$. Given this specification, it is possible to establish that for $v$ large enough relative to $\mu$, the equilibrium tax on capital can be higher under decentralization, and thus growth lower. Unfortunately, the $v$ and $\mu$ parameters are almost impossible to relate to the fundamentals of the stochastic process (generating a desire for diversification) and to interpret empirically.
fectly mobile across jurisdictions.\textsuperscript{4} Wildasin shows that in the steady state, the optimal tax set by a small jurisdiction is increasing in the adjustment cost parameter; i.e. taxes are higher, the less mobile over time is the physical capital stock. Becker and Rauscher (2007) extend this result to an endogenous infrastructure growth version of Wildasin’s model. Thus, in their model, growth is unambiguously lower, the less mobile over time is the physical capital stock. However, these papers do not calculate the outcome under centralized tax setting, and thus do not explicitly evaluate the effect of tax competition on growth.\textsuperscript{5}

Finally, the paper is also related to an existing literature on public finance in models of stochastic growth, where fiscal policy rules are taken to be fixed (Turnovsky, 2000 and Kenc, 2004). By contrast, in this paper, taxes are optimized by governments. So, this paper is the only one, to our knowledge, that studies endogenous tax policy in a stochastic growth model. For endogenous tax policy in a deterministic growth model, see Philippopoulos (2003) and Philippopoulos and Park (2003). But these papers do not deal with the issue of capital mobility and its impact on tax policy.

\textsuperscript{4}This is clear from the fact that in these models, there is a single “world” rate of return on household savings. Thus, household financial capital is distinct from the physical capital employed by firms. Physical capital is in fact, completely immobile between jurisdictions.

\textsuperscript{5}Becker and Rauscher claim that the adjustment cost parameter (b in their model) is a measure of inter-jurisdictional capital mobility, but this does not seem to be very plausible.
3. The Set-Up

3.1. The Model

We work with a dynamic stochastic version of the Zodrow-Mieszkowski (1986) model, where regional government use source-based capital taxes to finance the provision of a public good, which also has elements of the portfolio choice model of Merton (1969, 1971). The economy evolves in continuous time: \( t \in [0, \infty) \). There are \( n \) regions, \( i = 1, \ldots, n \). There is one firm in each region, which produces output from capital according to the constant returns production function. Expressed in differential form, changes in output in region \( i \) over the interval \((t, dt)\) is:

\[
   dy_i = k_i (dt + dz_i),
\]

where \( k_i \) is the capital stocks at \( t \), and the stochastic process\(^{6}\) \( z_i(t) \) is a Wiener process i.e. over the period \((t, dt)\), the change \( dz_i = z_i(t + dt) - z_i(t) \) is Normally distributed with variance \( \sigma_i^2 dt \) and zero mean, and non-overlapping increments are stochastically independent. Also, \( z_i(t), z_j(t) \) are independent for all \( i \neq j \).

Firms in region \( i \) are willing to operate at any scale iff, over any interval \((t, dt)\), the change in output per unit of capital \( dt + dz_i \), is equal to the cost of capital, which comprises the rental price of capital, \( r_i \), and the tax on the use of capital, \( \tau_i \). Thus, the rental price

\(^{6}\)The assumption that random shocks take the form of Brownian motion is standard in stochastic growth models. It describes a situation where productivity is subject to frequent small changes; see Turnovsky (2000) for more discussion.
of capital in region $i$ follows the process

$$dr_i = dt + dz_i - \tau_i dt = (1 - \tau_i) dt + dz_i.$$  

(3.1)

Each region is populated by a number of identical infinitely-lived households, and the population in each region is normalized to 1. In region $g_i$, each household has a flow of utility from private consumption and a public good:

$$u(c_i, g_i) = \ln c_i + \beta \ln g_i,$$  

(3.2)

where each of the two utility functions has the same fixed degree of relative risk-aversion equal to unity. At each $t$, the household in region $i$ has an endowment of the private good (wealth) $w_i$, which it can rent to any firm.

Finally, in region $i$, the public good is wholly financed by a source-based tax on capital i.e. $g_i = \tau_i k_i$. This is without loss of generality, as there is no wage income in the model, so our analysis would go through if $\tau_i$ were re-specified as an output tax. The tax is chosen by a benevolent government, that maximizes the sum of utilities of the households in its jurisdiction. The details of the two fiscal regimes are described in more detail below.

With decentralization, the $n$ governments play a stochastic differential game. As is usual in the literature on dynamic tax models, we focus on Markov strategies\footnote{Without the Markov restriction, there would be a very large number of equilibria; e.g. those sustained by punishment strategies.} in this game. These are strategies where $\tau_i$ is restricted to depend only on the state of the
economy, the vector of wealth variables \( w = (w_1, \ldots, w_n) \). Then, in this class of strategies, we focus on symmetric perfect equilibrium (Dockner et al., 2000). This requires that the \( \tau_i \) are mutual best responses conditional on any \( w \), and that in equilibrium, \( \tau_i = \tau \) and thus \( w_i = w \), for all \( i \). Finally, we guess initially that equilibrium strategies are state-independent, i.e. \( \tau_i \) is independent of \( w \), and we verify that this is true in equilibrium. This greatly simplifies the analysis by ensuring that the household faces a relatively simple savings and portfolio design problem.

Finally, we can now see more formally why in the absence of uncertainty \( (\sigma_i = 0) \), taxes and public good provision would be zero under decentralization. Without uncertainty, the households in any region will simply allocate its capital to the region where the return on savings is highest. Given the negative relationship between \( r \) and \( \tau \) in (3.1), it is then clear that all capital will flow into region(s) where \( \tau_i \) is lowest. This in turn implies that without mobility costs\(^8\), there will be a “race to the bottom” in capital taxes, with the only possible equilibrium tax being zero.\(^9\)

\(^8\)We cannot avoid this conclusion by assuming decreasing returns i.e. \( y = f(k) \), with \( f''(k) < 0 \), as then we are back to a Solow-type growth model, where taxes do not affect growth (in the long run).

\(^9\)Strictly speaking, a zero equilibrium tax is only possible if the marginal utility of the public good at zero provision is finite, which is not the case with logarithmic utility i.e. (3.2). A precise statement would be that there is no equilibrium with strictly positive taxes in this case.
3.2. Solving The Household Problem

Households solve a portfolio allocation/savings problem under uncertainty. Denoting $s_{ij}$ as the share of wealth, $w_i$, rented to the foreign firm, wealth evolves according to

$$dw_i = \sum_{j=1}^{n} s_{ij} w_i r_j dt - c_i dt,$$

where $\sum_j s_{ij} r_j dt$ is the overall return on wealth over the interval $(t, dt)$. Combining (3.1) and (3.3), we get:

$$dw_i = [\mu_i w_i - c_i] dt + w_i \sum_{j=1}^{n} s_{ij} dz_j,$$

where $\mu_i = \sum_j s_{ij}(1 - \tau_j)$ is the deterministic part (average) rate of return on wealth. Thus, household in region $i$ chooses $c_i$, $s_{ij}$ to maximize

$$E \left[ \int_{0}^{\infty} e^{-\rho t} u(c_i, g_i) \, dt \right]$$

subject to (3.2), (3.4) and $\sum_{j=1}^{n} s_{ij} = 1$. Note, in maximizing expected utility the household perceives public consumption $g_i$ to be given, although possibly time-varying, and also takes $\tau_i$ as fixed and time-invariant.

The solution to this problem is well-known (e.g., Jones and Manuelli, 2005) and easily stated. First, the optimal consumption rule is simply

$$c_i = \rho w_i$$

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Second, the portfolio shares $s_{ij}$, $j \neq i$ are determined by the $n-1$ first-order conditions

$$
\tau_i - \tau_j - \left[ \left( \sum_{j \neq i} s_{ij} - 1 \right) \sigma_i^2 + s_{ij} \sigma_j^2 \right] = 0, \quad j \neq i. \quad (3.7)
$$

To get intuition, consider the two-region case. Then, (3.7) solve for regions 1, 2 to give

$$
s_{12} = \frac{\tau_1 - \tau_2 + \sigma_1^2}{\sigma_1^2 + \sigma_2^2}, \quad s_{21} = \frac{\tau_2 - \tau_1 + \sigma_2^2}{\sigma_2^2 + \sigma_1^2}. \quad (3.8)
$$

The portfolio rule is simple and intuitive; invest more “abroad” (i.e. outside the home region $i$) (i) the higher the difference in average returns as measured by $\tau_i - \tau_j$, and (ii) the lower the relative uncertainty of investing abroad i.e. $\sigma_j^2/\sigma_i^2$. In the sequel, we simplify the analysis by assuming $\sigma_i = \sigma, i = 1, .. n$.

### 3.3. Fiscal Externalities

In this section, we identify the fiscal externalities at work in the model. For clarity, we focus on the two-region case ($n = 2$), thinking of region 1 as the home region. We trace the effects of a change in $\tau_2$ on home welfare. Then the portfolio allocation rule for home and foreign households is

$$
s_{12} = \frac{1}{2} + \frac{\tau_1 - \tau_2}{2\sigma^2}, \quad s_{21} = \frac{1}{2} + \frac{\tau_2 - \tau_1}{2\sigma^2}. \quad (3.9)
$$
Moreover the capital employed in the home region is

\[ k_1 = (1 - s_{12})w_1 + s_{21}w_2. \] (3.10)

Finally, in the home region, the household’s optimal accumulation of capital follows the rule (3.4), given also (3.6);

\[ dw_1 = w_1 [(\mu_1 - \rho) dt + (1 - s_{12})dz + s_{12}dz^*]. \]

By inspection of (3.4), (3.9), and (3.10), we can identify two fiscal externalities in the model.

First, increasing \( \tau_2 \) implies \( s_{21} \) up and \( s_{12} \) down from optimal portfolio choice, implying \( k_1 \) up. This is the well-known positive capital mobility externality: an increase in the foreign tax causes a capital outflow, benefitting the home region. Note that it is measured (inversely) by \( \sigma \); the higher \( \sigma \), the weaker is this externality, as the higher \( \sigma \), the stronger the incentive for the household to maintain a balanced portfolio.

Second, an increase in \( \tau_2 \) has other two related effects. First, it directly affects home welfare by lowering \( \mu_1 = 1 - (1 - s_{12})\tau_1 - s_{12}\tau_2 \), the deterministic part of the return on \( w_1 \). Second, it lowers \( \mu_2 \), and thus \( w_2 \) and thus \( k_1 \). We call this the negative rate of return externality. Note that the size of this externality is measured by \( s_{12}, s_{21} \) : specifically, this externality only operates in equilibrium if \( s_{12}, s_{21} > 0 \). But, the portfolio allocation rule ensures that at symmetric equilibrium, \( s_{12} = s_{21} = 0.5 \).
4. Equilibrium Taxes

4.1. Centralization

Following much of the literature in fiscal federalism (e.g., Lockwood, 2002, and Besley and Coate, 2003), we assume one of the defining characteristics of centralization is that taxes are set uniformly i.e. at the same level across regions. Such uniformity is widely observed in practice. So, from (3.7), with capital taxes being identical in all regions, each households invests an equal share of the savings in each region, i.e. \( s_{ij} = 1/n \). Then, from (3.4), an important simplification is that every wealth level \( w_i \) follows the same process, and so \( w_i = w \), implying a single state variable. Again from (3.4), this state variable evolves according to

\[
dw = w[1 - \tau - \rho] + wd\tilde{z}, \quad d\tilde{z} = \frac{1}{n} \sum_{j=1}^{n} dz_j \quad (4.1)
\]

Moreover, again as \( s_{ij} = 1/n \), capital employed in region \( i \) is equal to \( k_i = w \). Using all this information in addition to the consumption rule (3.6), instantaneous utility in region \( i \) is

\[
\ln c_i + \beta \ln g_i = \kappa + (1 + \beta) \ln w + \beta \ln \tau, \quad \kappa = \ln \rho. \quad (4.2)
\]
So, households in all regions have the same instantaneous utility (4.2), and this must therefore also be the objective of government. Formally, the central government chooses\(^{10}\) \(\tau\) to maximize

\[
E \left[ \int_0^{\infty} \left( (1 + \beta) \ln w_i + \beta \ln \tau \right) e^{-\rho t} dt \right]
\]

subject to (4.1). Setting up the Bellman equation, deriving the first-order condition, and guessing that the value function \(V(w)\) is linear in \(\ln w\), we can show (see the Appendix):

**Proposition 1.** The central equilibrium tax rate is

\[
\tau_c = \frac{\rho \beta}{1 + \beta}.
\]

The tax rate is increasing in the preference for the public good, \(\beta\), and the rate of discount, \(\rho\).

The comparative static results are intuitive. First, the higher the marginal valuation of the public good, the higher the tax. Second, the less the household values future growth i.e. the higher \(\rho\), the more it is willing to increase the tax rate to fund the public good now, at the expense of future growth in the tax base. Note finally that the centralized tax is independent of the number of regions.

\(^{10}\) In principle, \(\tau\) can be any function of \(w\), the state variable. But, given that \(V(w)\) is linear in \(\ln w\), it is computed in the proof of Proposition 1 that the optimal \(\tau\) is independent of \(w\). This is not due to the special log form for utility- it can be computed that \(\tau\) is independent of \(w\) also in the more general case where utilities from private and public consumption are iso-elastic (details available on request).
4.2. Decentralization

Here, the government in region \( i \) maximizes the expected discounted utility of the household in region \( i \) - given formally below - subject to the state equations (3.4), and arbitrary taxes \( \tau_j \), \( j \neq i \). Then, invoking symmetry, decentralized equilibrium is characterized by the solution to this problem when \( \tau_i = \tau \), all \( i \). But, is difficult to solve for government \( i \)'s problem given general taxes \( \tau_j \), \( j \neq i \). So, we assume that all regions \( j \neq i \) set the same tax \( \tau^* \), and solve for region \( i \)'s best response to \( \tau \), say \( \tau_i \). Then, imposing \( \tau_i = \tau^* \) gives a condition for the Nash equilibrium tax.

We proceed as follows. First, let \( s_{ij} = s \), \( j \neq i \), be the share of wealth invested by the households in region \( i \) in any region \( j \neq i \). Note that from (3.7), \( \tau_j = \tau^* \), \( j \neq i \), these share must all be the same. Indeed, evaluating (3.7) at \( \sigma_i = \sigma \), \( s_{ij} = s \), and \( \tau_i = \tau \), \( \tau_j = \tau^* \), and solving, we get

\[
s = \frac{\tau - \tau^*}{n\sigma^2} + \frac{1}{n}. \tag{4.3}
\]

Next, let \( s^* = s_{ji} \), \( j \neq i \), \( \hat{s} = s_{jk} \), \( k \neq j \neq i \) be the shares of wealth invested by the households in region \( j \neq i \) in region \( i \) and the \( n-2 \) regions \( k \neq j \neq i \) respectively. Again from (3.7), \( s^* \), \( \hat{s} \) solve the two simultaneous equations

\[
\tau^* - \tau - \sigma^2[-1 + 2s^* + (n - 2)\hat{s}] = 0 \tag{4.4}
\]

\[
-\sigma^2[-1 + (n - 1)\hat{s} + s^*] = 0. \tag{4.5}
\]
We are only interested in $s^*$. Solving (4.4) and (4.5), we get

$$s^* = \frac{(n-1)(\tau^* - \tau)}{n\sigma^2} + \frac{1}{n}.$$  

(4.6)

Now let $w$ be the wealth of region $i$, and $w^*$ be the average wealth of regions $j \neq i$. Then, by definition,

$$k = (1 - (n - 1)s)w + (n - 1)s^*w^*.$$  

(4.7)

Then, using the government budget constraint $g = \tau k$, and the consumption rule $c = \rho w$, region $i$’s instantaneous payoff can be written

$$\ln c_i + \beta \ln g_i = \kappa + \ln w + \beta \ln k + \beta \ln \tau.$$  

(4.8)

So, it is clear from (4.8) and (4.7) that there are two state variables in the problem, $w$ and $w^*$. These follow the following processes. First, from (3.4), given also (3.6), $\sigma_i = \sigma$, and the definition of $s$;

$$dw = w \left[(1 - (1 - (n - 1)s)\tau - (n - 1)s\tau^* - \rho)\ dt + (1 - (n - 1)s)dz_i + (n - 1)sdz^*\right],$$  

(4.9)

where $dz^* = \frac{1}{n-1} \sum_{j \neq i} dz_j$. Second, the process for some $w_j$ is

$$dw_j = w_j \left[(1 - (1 - s^*)\tau^* - s^*\tau - \rho)\ dt + s^*dz_i + (1 - s^* - (n - 2)s)dz_j + s \sum_{k \neq j \neq i} dz_k\right].$$  


As $w^* = \frac{1}{n-1} \sum_{j \neq i} w_j$, tedious but straightforward calculation gives

$$dw^* = \left[ (1 - (1 - s^*) \tau^* - s^* \tau - \rho) \right] dt + s^* dz + (1 - s^*) dz^*$.

(4.10)

So, the problem for the government of region $i$ is to choose $\tau$ to maximize

$$E \left[ \int_0^\infty \left( \ln w + \beta \ln \left( (1 - (n - 1)s)w + (n - 1)s^* w^* \right) + \beta \ln \tau \right) e^{-\rho t} dt \right]$$

subject to (4.9), (4.10), and the portfolio allocation rules (4.3) and (4.6).

Our approach to this problem follows Turnovsky (2000). We first write down the Bellman equation defining $V(w, w^*)$, and thus characterizing the optimal choice of $\tau$, given $\tau^*$. We then evaluate this Bellman equation at $\tau = \tau^*$. To get a closed-form solution for the equilibrium $\tau$, we must guess the correct form of the value function $V(w, w^*)$, which we are able to do, using the fact, from (4.9) and (4.10), that at a symmetric equilibrium ($s = s^* = \frac{1}{n}$), $w = w^*$. Specifically, we guess that $V(w, w) \equiv A + \psi \ln w$. All these steps are dealt with in detail in the Appendix, and the end result is:

**Proposition 2.** The decentralized equilibrium tax rate with $n$ regions is

$$\tau_d = \frac{\rho \beta}{\sigma^2} + \frac{1 + \beta}{n}.$$

(4.11)

The tax rate is increasing in the preference for the public good, $\beta$, the rate of discount,

\footnote{Note, the value function depends on the regions’ tax rate choices through private wealth.}
\( \rho \), and the size of the output shock, \( \sigma \).

A number of comments are in order here. This formula and the comparative statics are intuitive. First, as under centralization the higher the marginal valuation of the public good, the higher the tax and, the less the household values future growth (higher \( \rho \)), the more it is willing to increase the tax rate to fund the public good now. Second, the higher \( \sigma \), the weaker the response of the capital stock in any region to a change in the tax rate in that region (when \( n > 1 \)), and so the smaller the mobile tax base externality, thus increasing the equilibrium tax. Intuitively, the smaller the variance, the more willing are investors to move their wealth between regions in response to tax differences, thus increasing the mobility of the tax base.

More formally note from (4.7), in symmetric equilibrium,

\[
\frac{\partial k}{\partial \tau} = -(n - 1)w \frac{\partial s}{\partial \tau} + (n - 1)w^* \frac{\partial s^*}{\partial \tau}
\]

\[
= -(n - 1)w \frac{1}{n\sigma^2} - (n - 1)^2 w^* \frac{1}{n\sigma^2}
\]

\[
= -k(n - 1) \frac{1}{\sigma^2},
\]

(4.12)

where in the last line we used \( w = w^* = k \). So, the semi-elasticity \( \frac{1}{k} \frac{\partial k}{\partial \tau} = -(n - 1)/\sigma^2 \) is clearly decreasing in \( \sigma \). Note also that the more regions, the bigger this elasticity. This is a similar result to those for the standard static model of tax competition. Note finally this effect is operative only when \( n > 1 \); with no fiscal competition \( (n = 1) \), the size of stochastic shocks makes no difference to \( \tau \).
Last, we turn to a comparison of taxes under decentralization and centralization and how they relate to the number of regions \( n \). Inspection of (4.11) shows that \( n \) affects the denominator of \( \tau_d \) in two places, corresponding to the two different externalities identified above. First, a higher \( n \) increases the tax base elasticity, as already remarked; this is measured by the term \( \frac{\rho \beta (n-1)}{\sigma^2} \) which is simply \( \rho \beta \) times the semi-elasticity of the tax base with respect to \( \tau_d \).

Second, an increase in \( n \) increases the rate of return externality, corresponding to the term \( \frac{1}{n} (1 + \beta) \). Intuitively, any resident of region \( i \) only invests \( \frac{1}{n} \) of his wealth at home in equilibrium. So, the government of region \( i \) ignores the negative effect of the tax in region \( i \) on the rate of return to investors in all the other regions, measured by \( \frac{n-1}{n} (1 + \beta) \).

As the externalities have opposite effects on \( \tau_d \), we expect that the effect of \( n \) on \( \tau_d \) is not monotonic, and this is confirmed by the following result:

**Proposition 3.** There is a critical value of \( n \), \( \hat{n} \), such that \( \tau_d \) is higher than \( \tau_c \) for \( n < \hat{n} \), and lower than \( \tau_c \) for \( n > \hat{n} \). In particular, \( \tau_d \to 0 \) as \( n \to \infty \).

**Proof.** The denominator of (4.11), \( \frac{\rho \beta (n-1)}{\sigma^2} + \frac{1+\beta}{n} \), is a convex function of \( n \), with a minimum at \( n = \sqrt{\frac{(1+\beta)\sigma^2}{\rho \beta}} \). Thus, \( \tau_d \) must be a quasi-concave function of \( n \) with a maximum at \( n = \sqrt{\frac{(1+\beta)\sigma^2}{\rho \beta}} \). Note, \( \tau_c = \tau_d \) for \( n = 1 \). Also, \( \tau_d \to 0 \) as \( n \to \infty \) while \( \tau_c > 0 \), \( \forall n \). Thus, there always exists a value of \( \hat{n} \) with \( \tau_c \gtrless \tau_d \) if \( n \gtrless \hat{n} \). \( \square \)

Unlike the traditional tax competition model, the effect of \( n \) on \( \tau_d \) is generally ambiguous. This is of course, because an increase in \( n \) increases both the mobile tax base and rate of return externalities, which have opposite signs. So, for \( n \) small, the tax base
externality is small and so the rate of return externality dominates \((\tau_c < \tau_d)\), whereas for \(n\) large, the mobile tax externality dominates \((\tau_c > \tau_d)\).

Figure 4.1 illustrates the tax rate differential (assuming \(\beta = 1\) and \(\rho = 0.1\)). The thick is the centralized tax rate \(\tau_c\) which is independent of uncertainty. The thin lines depict the decentralized tax rates \(\tau_d\) for different levels of uncertainty. For instance, for \(\sigma^2 = 0.5\) the rate of return externality dominates the mobile tax externality for \(n \in \{2, 3, 4\}\).

The final step in our analysis is to relate taxes and growth. First, at any instant, output must be divided between private and public consumption, i.e. \(y = c + g\). Next, from the government budget constraint and (3.6), we have in symmetric equilibrium that \(y = \rho w + \tau k = (\rho + \tau)w\). So, the growth of output is just proportional to that of wealth.
Finally, from (4.10) and the definition of $dz^*$, in symmetric equilibrium:

$$dw = (1 - \tau - \rho)w + w \frac{1}{n} \sum dz_i.$$ 

Growth has a stochastic and deterministic component, and only the latter is affected by taxes, being decreasing in the tax. In what follows, we refer to $1 - \tau - \rho$ as the average growth rate.

So, Proposition 3 indicates that when the number of regions is less (greater) than $\hat{n}$, growth will be lower (higher) under decentralization than centralization. From Figure 4.1, when $\sigma = 0.5$, for example, $\hat{n} = 5$. Intuitively, it is only when $n > \hat{n}$ that the mobile tax base externality dominates and thus growth under decentralization is higher.

One further implication of the model concerns the relationship between the variance of stochastic shocks and growth. Under decentralization growth is decreasing in the variance of the output shock. This is consistent with the macroeconomic evidence (see Ramey and Ramey, 1995).

5. Infrastructure Public Goods

5.1. The Model

We now modify the baseline set-up by allowing the government to spend on a public infrastructure good rather than consumption good. For tractability, we assume two regions, unstarred (home) and starred (foreign). We will focus on the home region. Output
follows the process

\[ dy = g^{1-\alpha} k^\alpha (dt + dz). \]

There is a third factor of production (labelled as labor) which enters the production function with an exponent \( \alpha \). Labor is immobile and its supply is fixed at 1. Following Turnovsky (2000) and Kenc (2004), we assume that the pretax wage, \( a \), over the period \((t, t + dt)\) is determined at the start of the period and is equal to expected marginal product

\[ adt = (1 - \alpha)g^{1-\alpha}k^\alpha dt \]
\[ = (1 - \alpha)\tau^{1-\alpha}kdt \equiv \theta(\tau)kdt \quad (5.1) \]

using the budget constraint \( g = \tau k \). So, the wage is non-random. The rate of return (pre-tax) over the period \((t, t + dt)\) is thus determined residually:

\[ \frac{dy - adt}{k} = \alpha g^{1-\alpha}k^{\alpha-1}dt + g^{1-\alpha}k^{\alpha-1}dz \]
\[ = \alpha \tau^{1-\alpha}dt + \tau^{1-\alpha}dz \quad (5.2) \]

using the budget constraint \( g = \tau k \). So, the post-tax rate of return thus follows the process

\[ dR = (\alpha \tau^{1-\alpha} - \tau)dt + \tau^{1-\alpha}dz = r(\tau)dt + \tau^{1-\alpha}dz, \quad (5.3) \]

where \( r(\tau) = \alpha \tau^{1-\alpha} - \tau \) plays an important role below.
5.2. Solving the Household Problem

Now, setting $\beta = 0$ in (3.2), the consumer in the home region maximizes

$$E\left[\int_0^{\infty} e^{-\rho t} \ln c \, dt\right]$$

subject to the stochastic wealth equation

$$dw = (1 - s)wdR + swdR^* + adt - cdt$$

$$= [(1 - s)r(\tau) + sr(\tau^*)]wdt + \theta(\tau)kdt - cdt + (1 - s)w^{\tau-\alpha}dz + sw(\tau^*)^{1-\alpha}dz^*.$$  

Unlike consumption good case, this problem is non-standard, and so for completeness, we provide a solution in the Appendix. Moreover, in deriving the solution, we suppose that the household believes\textsuperscript{12} that $k \equiv w$, a belief which is true in equilibrium. The consumption and portfolio allocation rule for the home region are

$$c = \rho w, \quad s = \frac{(\tau^* - r)/\sigma^2 + \tau^{2(1-\alpha)}}{(\tau^{2(1-\alpha)} + (\tau^*)^{2(1-\alpha)})}. \quad (5.6)$$

We can now compare (5.6) to (3.9). The difference is only in the portfolio allocation rules; for comparison, the portfolio allocation rule in the consumption good model can be written $s = \frac{1}{2} + \frac{\tau^* - \tau}{2\sigma^2}$ in the notation of this Section. The difference between this formula

---
\textsuperscript{12}This assumption is slightly different than rational expectations, as when $\tau \neq \tau^*$, $k \neq w$ in general. However, we cannot solve the household problem in closed form under fully rational expectations when $\tau \neq \tau^*$.\---
and (5.6), therefore, is that in (5.6), $\tau, \tau^*$ affect the rule directly, and not just via their effects on $r, r^*$. This is because a higher tax rate in the home region increases the pre-tax rate of return on capital in the home region and thereby the riskiness of the investment from (5.3).

5.3. Fiscal Externalities

Besides the tax base externality and the rate-of-return externality identified in the AK-model, the infrastructure model exhibits a third type of externality. Infrastructure spending increases the return to capital and, as a result, from (5.3), we see that the stochastic, as well as the deterministic, part of the return on capital invested in a given region now depends positively on the tax rate. This is in contrast to the consumption good model, where the tax in a region only lowered the mean return on capital invested in that region, but did not affect the variance of returns.

Specifically, from inspection of (5.3), we see that a higher tax rate magnifies the exposure of investors to risk, i.e. the variance of the post-tax return to capital is increasing in the tax rate,

$$V(dR) = \left(\frac{\alpha}{\tau - \alpha}\right)^2 \sigma^2 dt.$$  \hfill (5.7)

Since each region also hosts capital from non-residents, this specification introduces a second negative externality, i.e. a higher tax increases the riskiness of investment and thus the risk-bearing of non-residents. We call this externality the risk-exposure externality. We will now characterize the equilibrium tax policy under (de)centralization and relate it
to the externalities.

5.4. Centralization

As in the consumption good case, we assume that taxes are set uniformly i.e. $\tau = \tau^*$. the same level across regions. So, from (5.6), each households invests an equal share of the savings in each region, i.e. $s = s^* = 0.5$. Then, from (5.5), $w = w^*$, and the the single state variable $w$ evolves according to

$$dw = [r(\tau) - \rho]wdt + \theta(\tau)kdt + w\tau^{1-\alpha}[0.5dz + 0.5dz^*].$$

(5.8)

where we have also used $k = w$. So, under centralization, the government maximizes

$$E\left[\int_{0}^{\infty} e^{-\rho t} \ln c \ dt\right] = E\left[\int_{0}^{\infty} e^{-\rho t} \ln w \ dt\right] + \frac{\ln \rho}{\rho}$$

subject to (5.8). The Bellman equation is

$$\rho V(w, w^*) = \max_{\tau} \left\{ \ln w + [r(\tau) + \theta(\tau) - \rho]V_{w}w + \frac{V_{ww}w^2}{2}\sigma_w^2 \right\},$$

(5.9)

where $\sigma_w^2 = 0.5\tau^{2(1-\alpha)}\sigma^2$. The first-order condition w.r.t. $\tau$ in (5.9) is

$$V_{w}w[r' + \theta'] + \frac{V_{ww}w^{2\tau^{2(1-\alpha)}\tau^{1-2\alpha}}}{2} = 0.$$

Now, we guess $V(w, w) = A + B \ln w$. Then, the first-order condition becomes, can-
celling $B$,  
\[ r'(\tau) + \theta'(\tau) - \frac{\sigma^2(1 - \alpha)\tau^{1-2\alpha}}{2} = 0. \]  
(5.10)

To interpret this condition, it is helpful to note that (following exactly the argument in the consumption case), the average growth rate in output is $r(\tau) - \rho$, where $r(\tau) = \alpha \tau^{1-\alpha} - \tau$ is a strictly concave function with a unique maximum at $\hat{\tau} = (\alpha(1 - \alpha))^{1/\alpha} > 0$.

Although (5.10) cannot be solved explicitly for the tax rate, we can see that in the absence of uncertainty, $r' + \theta' = 0$. As $\theta' = (1 - \alpha)^2 \tau^{-\alpha} > 0$ i.e. the tax has a positive effect on the wage, $r' < 0$. Thus, the tax rate is too high to be growth-maximising.

This reproduces the finding of Alesina and Rodrik (1994). Note that uncertainty implies $r' + \theta' > 0$, i.e. it tends to lower $\tau$. This is because an increase in $\tau$ raises the variance of the post-tax return on capital (5.7), and thus the riskiness of capital income. In consequence, the government can counteract the magnified exposure to income risk when then variance of the output shock $\sigma^2$ increases by selecting a lower tax rate. So, in principle, $\tau_C$ could maximize growth when there are stochastic shocks to production.

Note, the relationship between the variance of stochastic shocks and growth is not unambiguously negative. The negative relation between the output variance and the tax rate implies that a higher variance yields higher growth provided the interest rate adjusts negatively to an increase in taxes.

\[ ^{13}\text{In fact, invoking the implicit function theorem we find } \frac{d\tau}{d\sigma} < 0 \text{ if the share of output accruing to capital } \alpha \leq 0.5. \]
5.5. Decentralization

Here, the government in the home region maximizes the expected discounted utility of the home household subject to the state equations for \( w \) and \( w^* \), and equations determining \( k, k^*, s, s^* \), taking \( \tau^* \) as given. Specifically, using (5.6), the government in the home region maximizes

\[
E \left[ \int_0^\infty e^{-\rho t} \ln c \, dt \right] = E \left[ \int_0^\infty e^{-\rho t} \ln w \, dt \right] + \frac{\ln \rho}{\rho}
\]

It also understands that capital allocations are

\[
k = (1 - s)w + s^*w^*, \quad k^* = (1 - s^*)w^* + sw
\]

and portfolio shares are

\[
s = \frac{(r^*(\tau^*) - r^*(\tau))/\sigma^2 + \tau^{2(1-\alpha)}}{\tau^{2(1-\alpha)} + (\tau^*)^{2(1-\alpha)}}, \quad s^* = \frac{(r(\tau) - r^*(\tau^*))/\sigma^2 + (\tau^*)^{2(1-\alpha)}}{\tau^{2(1-\alpha)} + (\tau^*)^{2(1-\alpha)}}.
\]

The two state variables, \( w \) and \( w^* \) follow (5.5) and the counterpart of this equation for the foreign region. For completeness, we state both state equations:

\[
dw = [(1 - s)r(\tau) + sr^*(\tau) - \rho]wdt + \theta(\tau)kd\tau + (1 - s)w\tau^{1-\alpha}dz + sw(\tau^{1-\alpha})dz^*
\]

\[
dw^* = [(1 - s^*)r^*(\tau) + s^*r(\tau) - \rho]w^*dt + \theta(\tau^*)k^*d\tau + (1 - s^*)w^*(\tau^{1-\alpha})dz^* + s^*w^*(\tau^{1-\alpha})dz.
\]

Again, we set up the Bellman equation and guess the functional form of the value function in order to derive the first-order condition determining \( \tau \). All these steps are
dealt with in detail in the Appendix, and the resulting first-order condition, evaluated at symmetric equilibrium, is:

$$0.5r'(\tau) + \theta(\tau) + \theta(\tau) \frac{k_{r}}{K} - \frac{\sigma^2 (1 - \alpha) \tau^{1 - 2\alpha}}{4} = 0. \quad (5.14)$$

Finally, using (5.11) and (5.12), we can calculate;

$$k_r = -s_r w + s_w^* w^* \text{ and } s_r = -s_r^* = -\frac{r'}{2\sigma^2 \tau^2 (1 - \alpha)} + \frac{(1 - \alpha)}{2\tau}.$$

Thus, in symmetric equilibrium

$$\frac{k_r}{K} = \frac{r'}{\sigma^2 \tau^2 (1 - \alpha)} - \frac{(1 - \alpha)}{\tau}. \quad (5.15)$$

Comparing (5.15) to the centralized case, (5.10), one observes three differences:

- First, due to the mobile tax base externality, we have the term $\theta \frac{k_r}{K}$ in the FOC. $\frac{k_r}{K}$ measures the percentage capital outflow due to a 1 percentage point increase in the tax.

- Second, due to the rate of return externality, $r'$ enters with a weight of only 0.5. The rationale is that half of the total return to capital goes to foreigners and the effect of tax policy on it is external to the government.

- Third, a higher tax rate increases infrastructure spending and thus the exposure of investors to the productivity shock. The impact of capital taxation on risk exposure
of foreigners is not recognized (the risk exposure externality), explaining the weight of \( \frac{1}{4} \) rather than \( \frac{1}{2} \) in the last term.

Thus, in general the average growth rate of the economy, which is \( r(\tau) - \rho \), may be higher or lower under decentralization relative to centralization. To begin the comparison, we can obtain an analytical result confirming Hatfield (2006) when there is no uncertainty. First, by inspection, (5.10) reduces to \( r' = -\theta' \) when \( \sigma = 0 \). As \( \theta' = (1 - \alpha)^2 \tau^{-\alpha} > 0 \), but with centralization, \( r' < 0 \), and as \( r \) is single-peaked, this in turn implies that the tax is too high to be growth-maximising.

Next, combining (5.14) and (5.15), plus \( \theta = (1 - \alpha)\tau^{1-\alpha} \), we see that (5.14) reduces to

\[
r' \left( 0.5 + \frac{1 - \alpha}{\sigma^2 \tau^{1-\alpha}} \right) = \frac{\sigma^2 (1 - \alpha) \tau^{1-2\alpha}}{4}.
\]  

(5.16)

So, it is clear that as \( \sigma^2 \to 0 \), (5.16) reduces to \( r' = 0 \). Thus, with decentralization, in the absence of productivity shocks the government sets the tax rate so as to maximize \( r \) and thus the average growth rate \( r(\tau) - \rho \). This is Hatfield’s result. We can summarize as follows:

**Proposition 4.** If \( \sigma = 0 \), \( \tau_D = \hat{\tau} < \tau_C \), so the average growth rate is always higher under decentralization.

What happens with stochastic shocks? Although we cannot solve explicitly for the equilibrium tax rates \( \tau_C \) and \( \tau_D \), appealing to Proposition 4 and a continuity argument we know that \( \tau_C > \tau_D \) also holds for a small enough variance of the production shock.
This allows us to conclude that decentralization yields higher growth when the variance is small.

The latter finding does however not extend to any size of the variance. First, as see figure 5.1 shows, taxes fall as $\sigma$ increases in both fiscal regimes. With centralization, the reason is clear; a higher tax exposes investors to more risk, and this must be set against the productivity gain that the infrastructure good provides. This effect is also present with decentralization, although it only has half the impact, due to the risk exposure externality referred to above. Even so, it dominates any effect of $\sigma$ on the semi-elasticity of capital supply, (5.15). Generally, as $r' > 0$ for all $\sigma$ from (5.16), an increase in $\sigma$ makes the supply of capital more inelastic from (5.15), as in the consumption good case.

Note finally that as $k_x$ is independent of $\rho$ from (5.15), and as (5.10) and (5.14) are otherwise independent of $\rho$, then $\tau_D, \tau_C$ are also independent of $\rho$. This is in contrast to the consumption public good case where the trade-off between higher future growth
and more public consumption is decided in favor of more public consumption when $\rho$ rises. With infrastructure spending $\tau_D, \tau_C$ are independent of $\rho$ because taxation and infrastructure provision have countervailing effects on growth which are equated at the margin.

Now we turn to the relationship between decentralization and growth, recalling that the average growth rate is $r(\tau) - \rho$. Figure 5.2 shows how $r_C = r(\tau_C)$ and $r_D = r(\tau_D)$ vary as $\sigma$ increases. From figure 5.1 $\tau_C > \tau_D$. Since the growth rate is hump-shaped in taxes, the implication of the tax rate differential for growth can be ambiguous. Specifically, in the absence of uncertainty a decentralized government engages in Bertrand tax competition with the consequence of maximizing growth. The decentralized tax rate decreases as $\sigma$ increases and, since the growth rate is hump-shaped in the tax rate, growth is unambiguously decreasing in $\sigma$. 

Figure 5.2: $r_C$ (thin line) and $r_D$ (solid line) as a function of $\sigma$ for $\alpha = 0.5$. 

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A centralized government sets a too high tax rate to be growth maximizing in the absence of uncertainty\textsuperscript{14} and lowers it as $\sigma$ rises. For sufficiently small values of $\sigma$ growth is rising. In fact, for $\sigma \approx 1.7$ the growth rate equals that under decentralization and for $\sigma \approx 2$ the centralized tax rate is growth maximizing. For larger values both a decentralized and centralized government operate on the upward sloping part of the growth-curve with centralization yielding higher growth. This is in contrast to the results of Hatfield (2006), who assumes a deterministic growth model.

The simulation results indicate that a higher output variance yield lower growth in contrast to the finding under centralization. The reason is that decentralization maximizes the rate of return to investors (i.e. the interest rate) in the absence of shocks and a higher variance lowers the tax rate. Since the interest rate is hump-shaped in taxes, growth declines as the output variance increases.

6. Conclusions

This paper has considered the relationship between tax competition and growth in an endogenous growth model where there are stochastic shocks to productivity, and capital taxes fund a public good which may be for final consumption or an infrastructure input. Absent stochastic shocks, decentralized tax setting (two or more jurisdictions) maximizes the rate of growth, as the constant returns to scale present with endogenous growth implies Bertrand tax competition. Stochastic shocks imply that households face a portfolio choice.

\textsuperscript{14}This may imply a zero or even a negative net return to investors. The result is reminiscent of Alesina and Rodrick (1994).
problem. Shocks dampen down tax competition and may raise taxes above the centralized level when the government provides a public consumption good. Growth can be lower with decentralization. In the public infrastructure model shocks may increase the tax base elasticity and the equilibrium decentralized tax rate may be too low to yield higher growth with decentralization. Our results also predict a negative relationship between output volatility and growth, consistent with the empirical evidence.

One might ask how robust our results are. Two of our important simplifying assumptions are logarithmic utility of private consumption, and in the case of the infrastructure model, no taxes on labour. If logarithmic utility of private consumption is relaxed to iso-elastic utility, we can still solve the household savings and portfolio choice problem in closed form, but we cannot get a closed-form solution for the equilibrium tax, even in the case of a consumption public good. But the key externalities at work remain the same, and as a result, it is possible to get higher taxes and lower growth with decentralization in the public consumption good case\textsuperscript{15}. In the infrastructure model, we conjecture that our main conclusions would be unaffected, as long as the demand for the public good is high enough so that it is optimal to use a capital tax at the margin.

Finally, we should note that the two regimes can be unambiguously ranked in terms of welfare. To see this, note that the centralized solution can always replicate tax policy under decentralization. Appealing to a revealed preference argument, welfare under centralization is weakly higher than under decentralization. It would be interesting to set up a model in which not only the growth rate differential but also the welfare differential

\textsuperscript{15}Details of these calculations are available on request.
is ambiguous; e.g., due to inefficiencies in centralized decision-making. We leave such an exercise to future research.
References


A. Proofs of Propositions and Other Results

Proof of Proposition 1. There is a single state variable \( w \) which follows (4.1). So, denoting \( V(w) \) as the value function, the Bellman equation is

\[
V(w) = \max_{\tau} \left\{ (1 + \beta) \ln w + \beta \ln \tau + V_w \left[ (1 - \tau) - \rho \right] + \frac{V_{ww} w^2}{2} \frac{\sigma^2}{n} \right\}.
\]

Differentiating the RHS w.r.t. \( \tau \) and setting the result equal to zero, and assuming \( V(w) = A + \psi \ln w \), we have;

\[
\frac{\beta}{\tau} = V_w w = \psi.
\]

To derive \( \psi \) we rewrite the Bellman equation, using (A.1) and \( V(w) = A + \psi \ln w \) as;

\[
\rho (A + \psi \ln w) = (1 + \beta) \ln w + \beta \ln \tau + \xi [(1 - \tau) - \rho] - \frac{\xi \sigma^2}{2n}.
\]

Thus, equating coefficients on \( \ln w \), we see that \( \psi = \frac{1+\beta}{\rho} \). Combining with (A.1), the optimal tax rate is \( \tau = \frac{\rho \beta}{1+\beta} \) which completes the proof. □

Proof of Proposition 2. First rewrite the stochastic terms in the state equations as

\[
d\bar{w} = (1 - (n - 1)s)dz_i + (n - 1)sdz^s
\]

\[
d\bar{w}^s = s^*dz_i + (1 - s^*)dz^s
\]
Noting that
\[ E[(d_z)^2] = \sigma^2 dt, \quad E[(dz)^2] = \frac{\sigma^2}{n-1} dt, \quad E[dz_i dz_i] = 0 \]

one can compute from (A.2) and (A.3) that

\[
\begin{align*}
E[(d\tilde{w})^2] &= [(1 - (n - 1)s)^2 + (n - 1)s^2]\sigma^2 dt = \sigma_w^2 dt \\
E[(d\tilde{w}^*)^2] &= [(1 - s^*)^2/(n - 1) + (s^*)^2]\sigma^2 dt = \sigma_{w^*}^2 dt \\
E[d\tilde{w} d\tilde{w}^*] &= [(1 - (n - 1)s) s + (1 - s^*) s]\sigma^2 dt = \xi dt
\end{align*}
\]

So, assuming a value function \( V(w, w^*) \), the Bellman equation for the government problem can be written

\[
\rho V(w, w^*) = \max_{\tau} \{ \ln w + \beta \ln k + \beta \ln \tau + V_{\tau}w [1 - (1 - (n - 1)s)\tau - (n - 1)s\tau^* - \rho] \\
+ V_{w^*}w^* [1 - (1 - s^*)\tau^* - s^* \tau - \rho] + \frac{V_{ww}w^2}{2}\sigma_w^2 + \frac{V_{w^* w^*}(w^*)^2}{2}\sigma_{w^*}^2 + V_{ww^*}w w^* \xi \}
\]

where \( k = ((1 - (n - 1)s)w + (n - 1)s w^*) \). Taking into account the effect of \( \tau \) on \( s \) and \( s^* \) and, thus, on \( \sigma_w^2, \sigma_{w^*}^2 \), and \( \xi \), we have

\[
\begin{align*}
s_{\tau} &= \frac{1}{n\sigma^2}, \quad s_{\tau^*} = -\frac{n - 1}{n\sigma^2} \quad (A.5) \\
\frac{d\sigma_w^2}{d\tau} &= \frac{2(n - 1)}{n}[s n - 1], \quad \frac{d\sigma_{w^*}^2}{d\tau} = \frac{2}{n}[1 - ns^*] \quad (A.6) \\
\frac{d\xi}{d\tau} &= [(1 - ns^*) - (n - 1)(1 - ns)]\frac{1}{n} \quad (A.7)
\end{align*}
\]
So, using (A.5), the FOC for the tax is

\[
\frac{\beta}{\tau} + \frac{\beta k}{k} \frac{\partial k}{\partial \tau} - V_w w (1 - (n - 1) s) - V_{w*} w^* s^* + (V_w w + V_{w*} w^*) (n - 1) (\tau - \tau^*) \frac{1}{n \sigma^2} + \frac{1}{2} V_{ww} w^2 \frac{d \sigma^2_w}{d \tau} + \frac{V_{w*} w^* (w^*)^2}{2} \frac{d \sigma^2_{w*}}{d \tau} + V_{ww*} w w \frac{d \xi}{d \tau} = 0
\]

where

\[
\frac{\partial k}{\partial \tau} = -(n - 1) w s - (n - 1) w^* s^* = - (n - 1) w \frac{1}{n \sigma^2} + (n - 1)^2 w^* \frac{1}{n \sigma^2}
\]

At a symmetric equilibrium we have $\tau^* = \tau$ and so $w^* = w = k$ and $s = s^* = \frac{1}{n}$. Thus, using (A.9), and also noting from (A.6), (A.7) that as $\frac{d \sigma^2_w}{d \tau} = \frac{d \sigma^2_{w*}}{d \tau} = \frac{d \xi}{d \tau} = 0$, we can rewrite (A.8) as

\[
\frac{\beta}{\tau} - \frac{\beta (n - 1)}{\sigma^2} - \frac{1}{n} (V_w w + V_{w*} w^*) = 0
\]

Next, note that in symmetric equilibrium, $w = w^*$, and assume $V(w, w) \equiv A + \psi \ln w$. Then, at symmetric equilibrium,

\[
V_w w + V_{w*} w^* = \psi
\]

\[
V_{ww} w^2 + V_{w*} w^* (w^*)^2 + 2 V_{ww*} w w^* = -\psi
\]
and consequently, (A.10) can be rewritten as

\[
\frac{\beta}{\tau} - \frac{\beta(n-1)}{\sigma^2} - \frac{1}{n} \psi = 0 \tag{A.11}
\]

It just remains to solve for \( \psi \). Note also at symmetric equilibrium that \( \sigma^2_{w^*} = \xi = \frac{\sigma^2}{n} \). Using all these facts, the Bellman equation (A.4) reduces to

\[
\rho (A + \psi \ln w) = \{(1 + \beta) \ln w + \beta \ln \tau + \psi [1 - \tau - \rho] - \frac{1}{2n} \sigma^2 \psi \} \tag{A.12}
\]

So, by inspection, \( \psi = (1 + \beta)/\rho \). So, from (A.11) and \( \psi = (1 + \beta)/\rho \), we obtain the expression for \( \tau_d \) in Proposition 2. \( \square \)

**Derivation of the Solution to the Household Problem in the Public Infrastructure Good Case**

Using \( k = w \) in (5.5), the problem is to maximize (5.4) subject to

\[
dw = [(1 - s)r(\tau) + sr(\tau^*)]wdt + \theta w dt - cd t + (1 - s)w r^{1-\alpha} dz + sw(\tau^*)^{1-\alpha} dz^*. \tag{A.13}
\]

Assume the value function for this problem takes the form \( V(w) = A + B \ln w \). In this case the Bellman equation is

\[
\rho (A + B \ln w) = \max_{c,s} \left\{ \ln c + (w[(1 - s)r + sr^* + \theta] - c) \frac{B}{w} - \frac{B}{2} \sigma^2 \right\}
\]
where

\[\sigma_w^2 = [(1 - s)^2 \tau^{2(1-\alpha)} + s^2 (\tau^*)^{2(1-\alpha)}] \sigma^2.\]

is the variance of wealth. The first-order conditions for \(c\) and \(s\) are

\[\frac{1}{c} - \frac{B}{w} = 0 \quad (A.14)\]

\[B \left( r^* - r - \sigma^2 s (\tau^{2(1-\alpha)} + (\tau^*)^{2(1-\alpha)}) - \tau^{2(1-\alpha)} \right) = 0 \quad (A.15)\]

and the Bellman equation becomes

\[\rho (A + B \ln w) = \max_{c,s} \left\{ \ln w - \ln B + [(1 - s)r + sr^* + \theta]B - 1 - \frac{B}{2} \sigma_w^2 \right\}.\]

So, \(B = 1/\rho\); using this in \((A.14), (A.15)\) gives \((5.6)\). \(\square\)

**Derivation of the FOC \((5.14)\).** At a symmetric equilibrium, \(w = w^*\). So, the Bellman is

\[\rho V(w, w^*) = \max_{\tau} \left\{ \ln w + V_w\left[ ((1 - s)r(\tau) + sr(\tau^*) - \rho]w + \theta(\tau)k \right] \right.\]

\[+ V_{w^*}\left[ ((1 - s^*)r(\tau^*) + s^*r(\tau) - \rho]w^*dt + \theta(\tau^*)k^* \right] \right.\]

\[\left. + \frac{V_{ww^*}w^2}{2} \sigma_w^2 + \frac{V_{w^*w^*}w^*}{2} \sigma_{w^*}^2 + V_{ww^*}ww^* \xi \right\}\]

\[\sigma_w^2 = [(1 - s)^2 \tau^{2(1-\alpha)} + s^2 (\tau^*)^{2(1-\alpha)}] \sigma^2\]

\[\sigma_{w^*}^2 = [(1 - s^*)^2 (\tau^*)^{2(1-\alpha)} + s^2 (\tau^*)^{2(1-\alpha)}] \sigma^2\]

\[\xi = [(1 - s)s^* \tau^{2(1-\alpha)} + s(1 - s^*)(\tau^*)^{2(1-\alpha)}] \sigma^2\]

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Evaluated at $\tau = \tau^*$, the Bellman equation is

$$V_w[0.5r'w + \theta'k + \theta k_\tau] + V_{w^*}[0.5r'w^* + \theta k^*_\tau]$$
$$+ \left( \frac{V_{ww}w^2}{2} + \frac{V_{w^*w^*}(w^*)^2}{2} + V_{ww^*}ww^* \right) \frac{\sigma^2(1 - \alpha)\tau^{1-2\alpha}}{2}$$
$$= 0,$$

where we already used the fact that

$$\frac{\partial \sigma^2_w}{\partial \tau} = \frac{\partial \sigma^2_{w^*}}{\partial \tau} = \frac{\partial \xi}{\partial \tau} = \frac{\sigma^2(1 - \alpha)\tau^{1-2\alpha}}{2}.$$ 

Now, guess $V(w, w^*) = A + B \ln w$, i.e. the value function is independent of $w^*$. Then,

$$V_w = B, \quad V_{w^*} = 0$$
$$\left( \frac{V_{ww}w^2}{2} + \frac{V_{w^*w^*}(w^*)^2}{2} + V_{ww^*}ww^* \right) = -\frac{B}{2}.$$

Thus, the FOC becomes, cancelling $B$ and using $k = w$ in symmetric equilibrium:

$$0.5r' + \theta' + \theta k_\tau \frac{k}{k} - \frac{\sigma^2(1 - \alpha)\tau^{1-2\alpha}}{4} = 0.$$

as required. □